Journal Pre-proof

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DOI: 10.53759/7669/jmc202505028

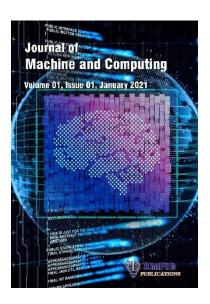
Reference: JMC202505028

Journal: Journal of Machine and Computing.

Received 02 July 2024

Revised form 30 September 2024

Accepted 25 November 2024



Please cite this article as: Srivinay, Swetha Parvatha Reddy Chandrasekhara, Amogh Pramod Kulkarni and Sneha S Bagalkot, "Targeted Brain-Computer Interface Utilisation by Employing Endogenous EEG Frameworks", Journal of Machine and Computing. (2025). Doi: https://doi.org/10.53759/7669/jmc202505028

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Targeted Brain-Computer Interface Utilisation by Employing Endogenous EEG Frameworks

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Abstract - Brain-computer interfaces (BCI) establish a direct communication link between the brain and communication link between the brain and computer interfaces (BCI) establish a direct communication link between the brain and computer interfaces (BCI) establish a direct communication link between the brain and computer interfaces (BCI) establish a direct communication link between the brain and computer interfaces (BCI) establish a direct communication link between the brain and computer interfaces (BCI) establish a direct communication link between the brain and computer interfaces (BCI) establish a direct communication link between the brain and computer interfaces (BCI) establish a direct communication link between the brain and computer interfaces (BCI) establish and computer interfaces external devices. These interfaces enhance human capabilities by either supplementing or replacing ral fun with potential applications in fields like rehabilitation, affective computing, robotics, gaming, and n global research efforts have led to standardized platforms that address the challeng non-linear brain dynamics, feature extraction, and classification. However, time-varying psycho-neur ations and their impact on brain signals present additional challenges in translating BCI technology fled laboratory settings to everyday use. This review provides an overview of recent advancements in the BC and outlines key challenges. In this paper, we propose a conceptual framework for personalized BCI application imed at improving the user experience by tailoring services to individual needs and preferences based on endogen coencephalography (EEG) paradigms, including motor imagery (MI), speech imagery (SI), and visual imagery he framework comprises two core components: user identification and intention classification, which allow f alized services by identifying users and recognizing their intended actions through EEG signals. We validate the f feasibility with a private EEG dataset from eight subjects, utilizing the ShallowConvNet architecture to o res. Experimental results show that user identification achieved an average classification accuracy intention classification reached 0.55 accuracy across all paradigms, with MI showing the ice. These results suggest that EEG signals can effectively support personalized BCI applications. identification and reliable intention decoding, ring s particularly for MI and SI.

Keywords - Brain-computer interfaces, Electroencephalo, aphy, psycho-neurophysiology, Brain Feature Extractions, Personalized BCI

LINTRODUCTION

Brain-Computer Interface (BCI) technology represents a cutting-edge field that bridges the gap between the human brain and external devices, enabling the state of munication and control through neural activity. BCIs operate by capturing electrical signals from the bain, decding them, and translating them into commands that can control devices such as computers, robotic limbs, or even assetive technologies [1]. This technology has enormous potential, particularly for individuals with neural rocal hasairm atts or disabilities, as it offers a way to restore lost functionalities, such as movement or communication, athous he need for conventional physical interfaces like hands or speech.

Neurologica and neuromatomical injuries and disorders impact millions of people globally, often resulting in movement impairments and the log of the ability to perform daily activities such as communicating, reaching, and grasping independency. People who have experienced neurological injuries, such as spinal cord injury (SCI), amyotrophic lateral scleosis, or so ke, can regain partial functionality through cortical prosthetic systems [2]. A cortical prosthesis is an end effect of device that receives action commands via a brain-computer interface (BCI), which records cortical activity and decodes aforeaction related to the intended action. These end effectors can range from virtual communication systems for the proposition of a person's limb through functional electrical stimulation

BCIs can be classified into invasive and non-invasive types, with invasive BCIs involving implanted electrodes to record neural signals with higher precision, while non-invasive BCIs utilize external methods, such as electroencephalography (EEG), to monitor brain activity. Despite the technological advancements, non-invasive BCIs remain more widely used due to their lower risk, although they often face challenges in signal clarity, resolution, and processing speed [3].

The application of BCIs spans a wide range of fields, from medical and rehabilitation to communication and entertainment. In healthcare, BCIs are being used to help individuals with conditions like paralysis, stroke, or amyotrophic lateral sclerosis (ALS) regain some degree of control over their environment [4]. BCIs are also integral to neuroprosthetics, which allow users to control robotic limbs or other assistive devices directly with their thoughts, offering the possibility of restoring lost mobility and independence.

Non-invasive brain imaging techniques, such as electroencephalography (EEG), magnetoencephalography (MEG), and functional magnetic resonance imaging (fMRI), have been applied in simpler BCI systems, such as low-throughput communication tools for spelling. However, these non-invasive methods often face limitations, including slow procest speeds (e.g., fMRI), low spatial resolution, limited signal bandwidth (e.g., EEG), and susceptibility to external artifacts [5]. Consequently, they are not ideal for complex, real-time applications like high-performance communication, corrol of multidimensional robotic limbs, or reanimation of paralyzed limbs for coordinated reaching and grasping. In correct, invasive BCIs, which offer higher resolution and greater signal bandwidth, provide the potential for idividuals when neurological injuries to naturally control more advanced systems and restore more intricate functions.

Electroencephalography (EEG) is a neurophysiological signal generated by neural activity in the best, providing insights into an individual's mental states and intentions. For decades, researchers have sought to ecode EGs, mals to understand these mental states and intentions. Recent advancements in deep learning have significantly enclosed the performance of EEG decoding [6]. Consequently, EEG-based brain-computer interface (BCI) technology, which enables the control of external devices based on a user's mental state or intention, has been extensively explored tooss various domains, showing promising potential for real-world applications [7].

Despite these advancements, research on personalized BCI applications the text of an individual's specific interests remains limited. Most existing BCI systems rely on generalized models the inaction quately address individual differences in interests, habits, and lifestyles, thus limiting their convenience and user a personal lowever, variations in EEG patterns among individuals present an opportunity to leverage this user-spectate interests to develop personalized BCI systems tailored to the unique characteristics and needs of each user-spectate.

To address this gap, we propose a conceptual freework of personanzed BCI applications, utilizing user-specific information through tasks such as user identification as into all classification. We further demonstrate the feasibility of this framework through preliminary experiments using a state endogenous EEG paradigm dataset.

A. YORK IN THIS AREA

BCI technology has diverse application in both crinical and non-clinical fields such as medicine, entertainment, education, and psychology, offering solution to be included to be included to be included the second to be included the processing speed, memory impairment, and reduced movement a litty in the elderly [8]. These issues can negatively impact the quality of life and mental health of older individuals. Over the past decade, several BCI applications have been developed to help seniors maintain a healthy life to be an easier of well-being.

BCIs can be categorised based on the type of electrodes used to measure brain activity: non-invasive BCIs, where electrodes are placed of the scan, ie.g., EEG-based BCIs), and invasive BCIs, where electrodes are implanted directly into the brain (e.g., ECoG on EEG). EEG-based BCIs are widely used for both synchronous and asynchronous control and communication. No evasive EEG-based BCIs are further classified into "evoked" BCIs, which rely on brain responses to external scandi (e.g., P300, SSVEP), and "spontaneous" BCIs, which analyze brain activity during mental tasks performed by transer voluntarily [9].

be expically consist of several components: signal acquisition, preprocessing, feature extraction, classification, anslation into commands, and user feedback. Open-source software tools like BCI2000, EEGLab, and FieldTrip have been developed to aid the processing and analysis of brain data, incorporating advanced signal processing and AI techniques [10]. Despite these advancements, BCIs face challenges such as low classification accuracy, limited degrees of reedom, and long training times.

To improve performance, hybrid BCIs (hBCIs) combining multiple modalities (e.g., P300 with SSVEP or MI) have been explored. These systems leverage the advantages of different brain activity signatures or combine brain signals with non-brain signals, such as eye movements (EOG), muscle activity (EMG), or heart signals (ECG). Closed-loop BCIs, which

provide real-time feedback, offer potential therapeutic benefits, such as enhancing cognitive abilities in elderly patients through biofeedback, potentially inducing cerebral plasticity and facilitating rehabilitation [11].

One major challenge is developing non-invasive BCI technologies for paralyzed patients, as non-invasive methods can suffer from weaker signals and lower signal-to-noise ratios. However, advanced techniques like deep learning can help address these issues by improving the decoding and extraction of relevant information from EEG signals. EEG-based BC have promising applications in motor control, psychological therapies, and monitoring conditions like smoking or alcoholabuse [12]. They are also being used in therapies for autism, memory capacity tests, and cognitive assessments.

The brain, which consists of the central nervous system (brain and spinal cord) and peripheral nervous system, has specialized regions that control various functions. BCIs leverage these brain regions to facilitate communicate a and control, offering hope for individuals with neuromuscular disorders. BCIs can restore or replace lost functions as ALS, cerebral palsy, stroke, or spinal cord injuries. Research continues to explore that pote tall for controlling prosthetic devices, robotic arms, and aiding rehabilitation, with the goal of improving quality of life for hose with disabilities [13].

III. COMPONENTS OF BCI

The components of BCI systems are broadly categorized into four main parts: signal acquision, processing, output, and feedback. The effectiveness of a BCI system largely depends on the signal acquisition redule, which is crucial for detecting and recording brain signals. This module is the primary focus of this paper.

The processing component analyses the recorded brain activity using percentage and algorithms to interpret the user's intended actions. It includes pre-processing techniques sets as interpret the component analysis and decoding methods that integrate machine learning approaches like appoint and the processing techniques sets as interpret the user's intended actions. It includes pre-processing techniques sets as interpret the user's intended actions. It includes pre-processing techniques sets as interpret the user's intended actions. It includes pre-processing techniques sets as interpret the user's intended actions. It includes pre-processing techniques sets as interpret the user's intended actions. It includes pre-processing techniques sets as interpret the user's intended actions. It includes pre-processing techniques sets as interpret the user's intended actions. It includes pre-processing techniques sets as interpret the user's intended actions. It includes pre-processing techniques sets as interpret the user's intended actions. It includes pre-processing techniques sets as interpret the user's intended actions. It includes pre-processing techniques sets as interpret the user's intended actions. It is included to the user's intended actions and the user's intended actions are user's intended actions. It is included actions and the user's intended actions are user's intended actions. It is included actions are user's intended actions and the user's intended actions are user's intended actions. It is included actions and the user's intended actions are user's intended actions and the user's intended actions are user's intended actions. It is included actions are user's intended a

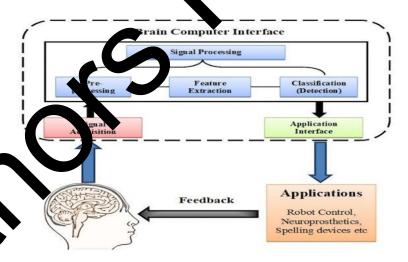


Figure 1. Components of a Brain Computer Interface [18]

Feature Extraction identifies meaningful patterns or features from the signals (e.g., time, frequency, or spatial features). Feature Classification decodes extracted features into user intentions using machine learning or statistical methods [16][17]. The output component translates the user's intended actions into real-world results, such as controlling a robotic arm or operating a speller, based on the processed information. The feedback component provides the user with information about the system's interpretation of their intended actions and the final execution results, using sensory feedback methods like visual or auditory cues.

IV. APPLICATIONS OF BCI

Brain-Computer Interface (BCI) technology is a rapidly advancing field with transformative potential to enhance human life, particularly in medicine. It enables individuals with physical disabilities to control machines through thought, restoring capabilities and independence. Collaboration between scientists and engineers is crucial to overcoming challenges and developing innovative applications. Beyond medicine, BCI has shown promise in industries like mining and education and is expected to drive advancements in robotics and neurophysiology. Additional applications include thought decode memory enhancement, telepathic communication, automation, and targeted medical treatments.

A. INTERPRETATION OF THOUGHTS

The human brain regulates thoughts and various physiological functions, some of which manifest extendly, like higher, while others remain internal and inaccessible. Current technologies cannot accurately interpret in vidua thoughts, but BCI holds promise in scenarios like criminology, where it could enhance polygraphs by in the tificial intelligence.

BCI's future potential includes translating thoughts into text, mapping imaginations it a tangible objects, according dreams, and creating wearable devices for monitoring thoughts or sleep patterns. It may also enter dividuals, particularly those with disabilities, to control machines like drones or vehicles using their thoughts [19].

However, as BCI technology advances, concerns about security and privacy will gree, necessitating universal regulatory standards. Further research and development are required to explore these costs. Lies fully.

B. ENHANCEMENT OF HUMAN MEMORY

Stephen Hawking proposed the idea of uploading the boan model into computer, raising the question of whether Brain-Computer Interface (BCI) technology could make the possible by extracting and decoding memory signals for storage in a computer. If successful, this could enable faster processing actrieval, and transmission of information, as well as control of external devices.

Recent BCI advancements show that brain signals can be converted into data reflecting human intentions, with future research exploring the extraction of behaviors and traits for scientific study. However, ethical guidelines must be followed in this research. If brain data can be accure elevated, it could be stored and retrieved from external devices, such as portable storage drives [20]. For example, a psychologist could use a BCI device to gain insights into a person's behaviour, providing more informed counselling, chieving a goal would require extensive multidisciplinary research.

C. MIND-TO-MIND ()MM. YICA YON

mbination with the computer-brain interface (CBI), could enable telepathic Rao et al. showed dividuals to communicate without physical or sensory channels. The integration of BCI and communicatio rface, which is still in early stages of development. Future research may expand telepathic CBI forms brain il garious fields and explore how human brains can be connected through the Internet of Things (IoT) communica hange [21]. Although some studies have investigated BCI-IoT interfacing, establishing brain-IoT for better in connectiv ignificant challenge. Further exploration of mind-to-mind and mind-to-machine interfaces is also diman-machine-human communication, with ethical considerations remaining central to these needed to adv ements

D. AUTOMATED CONTROL SYSTEMS

Advancements in BCI technology are showing promise for automation and control industries, including home automation, where it helps people with physical disabilities perform daily tasks independently. As BCI continues to develop, it is expected to positively impact industrial manufacturing, particularly through integration with secure wireless networks for automation. With rapid progress in sensor technology, BCI could also be applied in non-contact control and automation systems [22]. However, further research is needed to overcome BCI's limitations and ensure effective interaction with intelligent sensors.

E. KNOWLEDGE EXCHANGE

BCI, combined with CBI, could potentially enable brain reprogramming and intelligence sharing between individuals. While this concept may seem like science fiction, the principles behind the technology suggest it could be possible. However, achieving this requires a thorough understanding of brain function, which current scientific knowledge has not yet fully developed [23].

F. BRAIN POWER EXTRACTION

The human brain, despite constituting only 2% of the body's mass, uses about 20% of the body's total energy, making it the third most energy-intensive organ. It is suggested that BCI technology, in conjunction with other ac unced technologies, could harvest some of this energy to power low-energy external devices [24]. However, more searched to assess how much energy a typical BCI system could extract from the brain.

G. BOUNDED BRAIN-COMPUTER INTERFACE

In BCI systems, electrodes capture all brain signals in their vicinity, leading to a large amount a noise of making signal processing difficult. By localizing the system to focus on specific brain signals for a segeted ody part, such as placing it near speech-related areas in individuals with speech impairments, the system's performance could improve, and its size could be reduced [25].

V. DIFFICULTIES

A. NEUROLOGICAL AND PSYCHOPHYSIOL CITE. DIA CULTIES

Emotional, mental, neurophysiological, and neurophysical ectors significantly impact BCI performance, leading to variability both within and between individuals. Psychological factors such as attention, memory load, fatigue, and motivation, as well as personal traits like lifestyle, gender, and age, influence brain dynamics and BCI performance. For instance, individuals with lower empathy tend to generate high P300 wave amplitudes than those with greater empathy. Additionally, resting-state physiological parameters, such as heart rate variability and brain network dynamics, also affect BCI performance.

BCI performance is linked to neuro atomical psychological factors, such as gray matter volume in sensorimotor cortical areas, and physiological predictrs like spectral entropy from EEG recordings. Around 15–30% of individuals struggle to produce strong entropy as a last operate a BCI, which may be influenced by both neurophysiological and technological factors. Adap we machine learning approaches could help reduce BCI illiteracy by considering both physiological and psychological traits.

Case-specific results is not led to address challenges like BCI illiteracy and to improve stroke rehabilitation using customized constructions systems that account for individual brain function. Although current neuroimaging techniques can identify lesion sites, and red Boolesigns are necessary for effective rehabilitation, but this individualized approach limits broader implementation.

R. TECHNICAL DIFFICULTIES

Event-related potentials (ERP), steady-state visual evoked potential (SSVEP), auditory evoked potential (AEP), steady-state somatosensory evoked potential (SSSEP), and motor imagery (MI) are used to detect cognitive signatures in BCIs, but none work universally for all applications. ERPs and SSVEPs depend on external stimuli and may not be effective for individuals with impaired visual processing, whereas auditory-based ERPs could be an alternative. SSVEP offers high information transfer but suffers from visual fatigue and non-intuitive control signals. MI-based BCIs are slower, limiting their use in real-time environments like virtual reality.

Hybrid BCIs combining different signatures (e.g., SSVEP/ERP, SSVEP/MI) offer improved performance, but asynchronous BCIs still struggle. Brain dynamics' inherent instability complicates BCI systems, which rely on signal acquisition, processing, and effector devices. EEG-based systems, though cost-effective and portable, have low spatial resolution. High-density EEG improves resolution but increases computational demands. Combining EEG with other methods like fNIRS enhances performance, but fNIRS alone is inadequate. MEG offers better spatiotemporal resolution but is more expensive. Classifier design in BCIs faces challenges like dimensionality issues, bias-variance trade-offs, a covariate shifts, which can be addressed through adaptive methods and transfer learning.

VI. PROPOSED METHODOLOGY

A. DUTIES OF THE TAILORED BCI APPLICATION

The primary objective of the proposed framework is to deliver personalized BCI applications to each included user. To accomplish this, we propose that the application should possess two key capabilities. User dentification to assess user preferences, and ii) intention classification to carry out the user's intended action.

i. USER IDENTIFICATION TO ASSESS USER PREFERENCES

User identification involves determining the individual using the application, which serves as an initial step in understanding their preferences. Similar to other bio signals, EEG chala chibit abject variability, meaning that EEG features can differ between individuals, even when they are in the tame in

ii. INTENTION CLASSIFICATION TO CARRY OF THE USER'S INTENDED ACTION

User identification involves determining the individual using the application, which serves as an initial step in understanding their preferences. Similar to take bio signals, EEG signals exhibit subject variability, meaning that EEG features can differ between individuals, even where they are in the same mental state or performing identical tasks. By capitalizing on this variability, user-specific and features can be extracted and used for identification, enabling the BCI application to adjust to the unique characteristic and ach user.

B. PERSONALIZED F A AN ICA YON FRAMEWORK

Fig 2. illustrates the overall workflow of the proposed framework, designed to deliver personalized user-intended services through the Bouppy cathe. When a deer interacts with the system using an endogenous EEG paradigm, the corresponding EEG signals served input to processing.

The user identication is del extracts user-specific information from the database, analysing preferences. Simultaneously, the intention identication model deciphers the user's intended action and triggers the relevant application programming interface (Arcation that action. By combining the user's preferences with the identified API, the framework delivers a personalized By service.

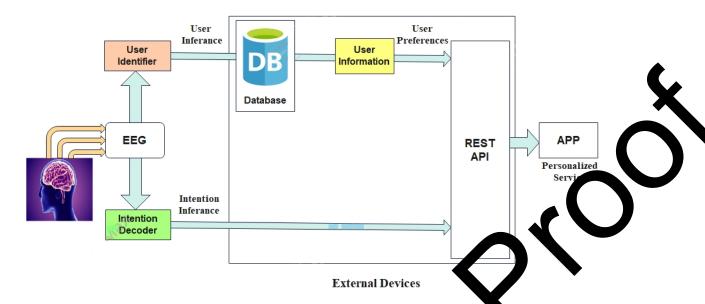


Fig 2. Overview of the proposed framework. The user identification and intention classification model processes EEG signals as input and provides personalized BCI services based on the user's information and detected intention.

This process is mathematically expressed as follows:

$$p(s) = f(x)$$
(1)
 $p(c) = g(x)$ (3)
 $p(cs) = h(p(p(c)|p(s)))$ (3)

Here, x represents the input EEG signal; $f(\cdot)$ of p(s) denote the user identification model and the predicted user class, respectively. Similarly, $g(\cdot)$ and p(c) correspond to the intention classification model and the predicted intention class. The function h(p(p(c)|p(s))) represents the ARI process, conditioned on the predicted user class. Finally, p(cs) represents the output, delivering the personalized action result for the BCI application.

VI EXPERIMENTAL ANALYSIS & RESULTS

To assess the feasible ty of the poposed framework, we conducted experiments to evaluate the reliability of its two primary tasks—user antification and intention classification—using a private dataset.

A. A QUIS. N OF EEG DATA

We gathered F G signals from eight participants (four males and four females, aged 26.4 ± 1.7 years) using three types of redogenous EG paradigms—Motor Imagery (MI), Somatosensory Imagery (SI), and Visual Imagery (VI)—to create a polarisate for our experiments. All participants were healthy with no history of neurophysiological disorders and voluntarily took part in the study, which was reviewed and approved by the Institutional Review Board of Korea University [KUIRB-2024-0065-01]. During the experiment, participants were instructed to perform the three types of endogenous EEG paradigms based on prompts displayed on a monitor. Each trial involved presenting a target imagery class and paradigm for two seconds, followed by a two-second fixation cross to stabilize EEG responses. Participants then imagined the target class for three seconds during a blank screen, with a final two-second fixation cross to clear residual EEG activity.

B. MODELS FOR EEG DECODING

ShallowConvNet [24] architecture was used as the EEG decoding model for user identification and intention classification tasks, leveraging its versatility in decoding EEG features. The model was trained to identify subjects for user identification and classify signals into four imagery classes for intention classification, with cross-entropy loss used for optimization in both tasks.

C. MODEL TRAINING

The training dataset for the user identification task was created by shuffling all EEG trials from all subjects and splitting them into 70% training, 10% validation, and 20% test sets. For the intention classification task, EEG trials from six subjects were used for training, with the remaining trials from two subjects used for validation and testing. Both models were with a learning rate of 0.001, weight decay of 0.001, batch size of 64, and the Adam optimizer for 100 epochs. To revent overfitting, the models were validated at each epoch using the validation set.

Subject	Paradigm				
	MI	SI	VI	Oy all	
S1	0.999	0.998	0.999	.999	
S2	0.998	0.999	0.998	0.998	
S3	0.998	0.994	0.997	297	
S4	0.994	0.997	0.999	0.998	
S5	0.995	0.996	770	0.996	
S6	0.997	0.995	0.99	0.995	
S7	0.994	0.998	95	0.995	
S8	0.994	0.994	0. 4	0.996	
Mean	0.99613	791	0.99638	0.99675	

Table 1. Accuracy of User Identification by Endogenous Paradigms

Table 2. Accuracy of Intent. Classification by Endogenous Paradigms

Subject	Paradigm				
	ML	SI	VI	Overall	
S1	9 46	0.47	0.38	0.39	
S2	15	0.39	0.39	0.39	
S3	0.45	0.55	0.39	0.40	
S4	0.95	0.81	0.67	0.70	
S5	51	0.45	0.77	0.61	
S6	0.3	0.46	0.47	0.55	
S7	0.95	0.87	0.59	0.80	
28	0.68	0.65	0.68	0.57	
Me	0.6375	0.58125	0.5425	0.55125	

D. SSES. MENT METHOD

The todel's programme for each task was evaluated using average classification accuracy. For the user identification model, erformance was assessed by combining EEG trials from all subjects and applying five-fold cross-validation. For intention classification model, performance was evaluated using five-fold cross-validation for each subject with a second pendent BCI configuration.

VIII FINDINGS AND ANALYSIS

A. EFFICACY OF USER IDENTIFICATION

The experimental findings for user identification tasks are shown in Table I. With an average classification accuracy of 0.996, the user identification performance was consistently dependable across all subjects and EEG paradigms, as the table

illustrates. These findings suggest that by utilising unique EEG characteristics that are personal to each person, EEG signals can be a reliable method for determining user-specific information and preferences.

B. EFFICACY OF INTENTION CLASSIFICATION

The experiment's findings for the intention categorisation task are shown in Table II. All paradigms combined had a overall classification accuracy of 0.58. With a mean performance of 0.64, MI outperformed SI and VI among the three endogenous paradigms, even though it used a straightforward ShallowConvNet model as the decoding model with no task specific techniques or fine-tuning.

The mean accuracy for VI was 0.54, the lowest performance for SI, which had a mean performance of 0.58. According to these findings, MI and SI may be trustworthy endogenous paradigms for expressing user intention as a natural pode of communication. Subject 6 performed the best among the participants in each of the three paradigms. Despite his ing a worse performance in VI, Subject 4 also demonstrated consistent performance in MI and SI. Although they demonstrated as well as subjects 6 and 4, subjects 1, 2, 3, 5, 7, and 8 nevertheless showed promise for employing endogenous EEG paradigms with accuracies higher than chance levels.

IX CONCLUSION

In this research, we propose a conceptual framework for a personalised BCI application uses endogenous paradigms to identify users and provide customised services depending on user input. Additionally, g experiments on private datasets, we show that the two main goals in our framework—user identification and ention classification—are feasible. Recommendation algorithms could be improved and more accurate and d personalisation could be achieved by combining user feedback mechanisms with additional bio signals, such ast user activity data. Our upcoming research will concentrate on improving classification performance us EEG decoding models, adding taskspecific optimisations, and putting the suggested framework into -time BCI application. We will also actic integrate user feedback and leverage user data to improve

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